Eigen(singular)-vector distribution of anisotropic random matrices

Jun Yin<br>UW-Madison

HKU, Jan-2015

## Anisotropic matrix:

case 1:

$$
Y:=T X
$$

where $T$ is deterministic matrix and $X$ is i.i.d random matrix such that $\mathbb{E} X_{i j}=0$.
case 2:

$$
Y:=X+A
$$

where $A$ is deterministic symmetric matrix and $X$ is a Wigner random matrix.

## Asymptotically close

We say that $\left\{\mathbf{u}_{n}\right\}_{n=1}^{\infty}$ is asymptotic close to $\left\{\mathbf{v}_{n}\right\}_{n=1}^{\infty}, n \rightarrow \infty$ if

1. $\mathbf{u}_{n} \in \mathbb{R}^{d_{n}}, \mathbf{v}_{n} \in \mathbb{R}^{d_{n}}, d_{n} \rightarrow \infty$
2. for any sequence of fixed dimensional subspace

$$
\left\{S_{n} \subset \mathbb{R}^{d_{n}}: \quad \operatorname{dim}\left(S_{n}\right)=k\right\}_{n=1}^{\infty}
$$

we have

$$
\lim _{n} f\left(\left.\mathbf{u}_{n}\right|_{S_{n}}\right)-f\left(\left.\mathbf{v}_{n}\right|_{S_{n}}\right)=0
$$

for any continuous bounded function $f: \mathbb{R}^{k} \rightarrow \mathbb{R}$.

## Isotropic matrix:

Wigner matrix: Let $W_{n}$ be a $n \times n$ Wigner matrix and $\mathbf{u}_{k, n}$ be the normalized $k$-th eigenvector of $W_{n}$. For sequence $k_{n} \in[[1, n]]$

$$
\sqrt{n} \mathbf{u}_{k_{n}, n} \rightarrow \mathbf{v}_{n} \sim \mathcal{N}\left(0, I_{n}\right)
$$

Edge case: $k_{n}=o(n)$, [Knowles, Y, 2010] Green's function comparison method.

Bulk case: [Yau, Bourgade, 2014] Moment flow method.

Note: the "limit" is independent of the entry-distribution of $W_{n}$.

## Isotropic "limit"

For Wigner matrix, any eigenvector is asymptotically close to

$$
\mathbf{v}_{n} \sim \mathcal{N}\left(0, I_{n}\right)
$$

which is orthogonal transform invariant, i.e,

$$
\mathbf{v}_{n} \sim O \mathbf{v}_{n}
$$

It is easy to understand this result in the Gaussian case, since

$$
W^{G} \sim O^{*} W^{G} O
$$

## I.i.d matrix $X_{m \times n}$ :

Recall: non-zero singular values of $X$ are non-zero eigenvalues of $X X^{*}$ and $X^{*} X$.

Non-zero-left-singular vectors of $X$ are eigenvectors of $X X^{*}$ whose eigenvalues are not zero.

Non-zero-right-singular vectors of $X$ are eigenvectors of $X^{*} X$ whose eigenvalues are not zero.

Let $\mathbf{u}_{k, n}$ be the $k$-th non-zero-left-singular vector of $X_{m \times n}, \log m \sim$ $\log n$. For sequence $k_{n}$

$$
\sqrt{m} \mathbf{u}_{k_{n}, n} \rightarrow \mathbf{v}_{n} \sim \mathcal{N}\left(0, I_{m}\right)
$$

Let $\mathbf{u}_{k, n}$ be the $k$-th non-zero-right-singular vector of $X_{m \times n}$, $\log m \sim \log n$.

$$
\sqrt{n} \mathbf{u}_{k_{n}, n} \rightarrow \mathbf{v}_{n} \sim \mathcal{N}\left(0, I_{n}\right)
$$

Singular vector of anisotropic matrix:
Let $Y_{m \times n}=T X$, where $T$ is $m \times \hat{m}$ deterministic matrix and $X$ is i.i.d. $(\hat{m} \times n)$ random matrix such that $\mathbb{E} X_{i j}=0$. We assume $\log m \sim \log n$.

Let $\mathbf{u}_{k, n}$ be the $k$-th right singular vector of $Y_{m \times n}$.

$$
\sqrt{n} \mathbf{u}_{k_{n}, n} \rightarrow \mathbf{v}_{n} \sim \mathcal{N}\left(0, I_{n}\right)
$$

Let $\mathbf{u}_{k, n}$ be the $k$-th left singular vector of $Y_{m \times n}$.

$$
\sqrt{m} \mathbf{u}_{k_{n}, n} \rightarrow \mathbf{v}_{n} \sim \mathcal{N}\left(0, \frac{m / n}{\gamma_{k_{n}, n}}\left|\frac{T}{1+m\left(\gamma_{k_{n}, n}\right)|T|^{2}}\right|^{2}\right)
$$

where $\lambda_{k_{n}, n}$ is the singular value w.r.t. $\mathbf{u}_{k_{n}, n}$ and $\gamma_{k_{n}, n}$ is its classical location. And

$$
m(x) \in \mathbb{C}: m(x)^{-1}=-x+\frac{1}{n} \operatorname{Tr} \frac{|T|^{2}}{1+m(x)|T|^{2}}, \quad \operatorname{Im} m(x) \geqslant 0
$$

[Knowles, Y, 2014]

$$
\begin{gathered}
\sqrt{m} \mathbf{u}_{k_{n}, n} \rightarrow \mathbf{v}_{n} \sim \mathcal{N}\left(0, \frac{m / n}{\gamma_{k_{n}, n}}\left|\frac{T}{1+m\left(\gamma_{k_{n}, n}\right)|T|^{2}}\right|^{2}\right) \\
m(x) \in \mathbb{C}: m(x)^{-1}=-x+\frac{1}{n} \operatorname{Tr} \frac{|T|^{2}}{1+m(x)|T|^{2}}, \quad \operatorname{Im} m(x) \geqslant 0
\end{gathered}
$$

Note: the "limit" only depends on $T T^{*}$.

Note: Since $T=U D V$, one only need to study the singular vector of $Y^{\prime}=D V X$.

$$
\sqrt{m} \mathbf{u}_{k_{n}, n}^{\prime} \rightarrow \mathbf{v}_{n} \sim \mathcal{N}\left(0, \frac{m / n}{\gamma_{k_{n}, n}}\left|\frac{D}{1+m\left(\gamma_{k_{n}, n}\right)|D|^{2}}\right|^{2}\right)
$$

where the covariance matrix is diagonal, as people believed.

Let $Y_{n \times n}=X+A$, where $A$ is $n \times n$ deterministic symmetric matrix and $X$ is a Wigner matrix such that $\mathbb{E} X_{i j}=0, \mathbb{E} X_{i j}^{2}=1 / n$.

Let $\mathbf{u}_{k, n}$ be the $k$-th eigen-vector of $Y_{m \times n}$.

$$
\sqrt{n} \mathbf{u}_{k_{n}, n} \rightarrow \mathbf{v}_{n} \sim \mathcal{N}\binom{0,}{m\left(\gamma_{k_{n}, n}\right)+A-\gamma_{k_{n}, n}}
$$

where

$$
m(x) \in \mathbb{C}: m(x)=\frac{1}{n} \operatorname{Tr}(-m(x)+A-x)^{-1}, \quad \operatorname{Im} m(x) \geqslant 0
$$

[Knowles, Y, 2014]

## Universality:

For $Y=T X$, the asymptotic behavior of singular-vectors are independent of

1. The distribution of entries of $X$,
2. The right singular vector of $T$, i.e., only depends on $T T^{*}$.
(Actually it depends on left singular vector in a very trivial way)

To understand this universality phenomenon, we developed a new comparison method: self-consistent comparison method.

## Old: Lindeberg comparison method

For comparing two $m \times n$ random matrices $X_{i j}$ and $\widetilde{X}_{i j}$, one constructs $m n+1$ new matrices $Y^{[k]}$. First, define an order for entries:

For example: We say $(i, j)$ is the $\phi(i, j)$-th entry, with $\phi(i, j)=$ $i \times n+j$.

Random matrices $Y^{[k]}$ are defined as: the "first" $k$ entries of $Y^{[k]}$ have the same distribution as entries of $X$, the others have the same distribution as those of $\widetilde{X}$.

Advantage: The difference between $Y^{[k]}$ and $Y^{[k+1]}$ is just one entry.

$$
F(X)-F(\widetilde{X})=\sum_{k}\left(F\left(Y^{[k]}\right)-F\left(Y^{[k+1]}\right)\right)
$$

Perturbation theory

Disadvantage:

1. The local law (or some prior bound) of $Y^{[k]}$ are needed for this method, i.e., one need to use other methods to derive the local law for $Y^{[k]}$ first.
2. The distance between $Y^{[k]}$ and $Y^{[k+1]}$ can not be arbitrary small.

We need a continuous self consistent version of comparison method.

## Self consistent comparison method

Suppose there are two collections $X^{0}=\left(X_{i}^{0}\right)_{i \in \mathcal{J}}$ and $X^{1}=$ $\left(X_{i}^{1}\right)_{i \in \mathcal{J}}$ of random variables indexed by some finite set $\mathcal{J}$. We need to estimate

$$
\mathbb{E} F\left(X^{1}\right)-\mathbb{E} F\left(X^{0}\right)
$$

For example: we can derive large derivation bound by choosing

$$
F(X):=\left(|\mathcal{T}|^{-1 / 2} \sum_{i \in \mathcal{J}} X_{i}\right)^{2 p}
$$

We construct a continuous family $\left(X^{\theta}\right)_{\theta \in[0,1]}$ such that

$$
X_{i}^{\theta} \sim \chi_{i}^{\theta} X_{i}^{1}+\left(1-\chi_{i}^{\theta}\right) X_{i}^{0}
$$

where $\chi_{i}^{\theta}$ are i.i.d r.v. such that $\mathbb{P}\left(\chi_{i}^{\theta}=1\right)=\theta$ and $\mathbb{P}\left(\chi_{i}^{\theta}=0\right)=$ $1-\theta . X_{i}^{\theta}$ has probability $\theta$ to have the same distribution as $X_{i}^{1}$, otherwise it has distribution of $X_{i}^{0}$.

$$
\rho_{X_{i}^{\theta}}=\theta \rho_{X_{i}^{1}}+(1-\theta) \rho_{X_{i}^{0}}
$$

With

$$
X_{i}^{\theta} \sim \chi_{i}^{\theta} X_{i}^{1}+\left(1-\chi_{i}^{\theta}\right) X_{i}^{0}
$$

we have

$$
\begin{aligned}
& \mathbb{E} F\left(X^{1}\right)-\mathbb{E} F\left(X^{0}\right)=\int \frac{\partial}{\partial \theta} \mathbb{E} F\left(X^{\theta}\right) \mathrm{d} \theta \\
& =\int \sum_{i \in \mathcal{J}}\left(\mathbb{E} F\left(X^{\theta, i, 1}\right)-\mathbb{E} F\left(X^{\theta, i, 0}\right)\right) \mathrm{d} \theta
\end{aligned}
$$

where
$X^{\theta, i, 1}$ is defined as $X^{\theta}$ except $X_{i}^{\theta, i, 1} \sim X_{i}^{1}$
$X^{\theta, i, 0}$ is defined as $X^{\theta}$ except $X_{i}^{\theta, i, 0} \sim X_{i}^{0}$
With Taylor's expansion, we can replace $\mathbb{E} F\left(X^{\theta, i, 1}\right), \mathbb{E} F\left(X^{\theta, i, 0}\right)$ back to $\mathbb{E} F\left(X^{\theta}\right)$.

We have an identity of the form

$$
\begin{equation*}
\frac{\partial}{\partial \theta} \mathbb{E} F\left(X^{\theta}\right)=\sum_{n \geqslant 1} K_{n} \sum_{i \in \mathcal{J}} \mathbb{E}\left(\frac{\partial}{\partial X_{i}^{\theta}}\right)^{n} F\left(X^{\theta}\right) \tag{1}
\end{equation*}
$$

where the constant $K_{n}$ depends only on the first $n$ moments of $X^{0}$ and $X^{1}, K_{n}=0$ if the first $n$ moments of $X^{1}$ and $X^{0}$ match.

Note: it is self-consistent in the sense that the right-hand side depends on the quantities to be estimated.

It is level-1: only $X^{\theta}$ appears on both sides.

## Simple Example:

Let's prove $C L T$ by choosing $F(X):=f\left(|\mathcal{J}|^{-1 / 2} \sum_{i \in \mathcal{J}} X_{i}\right)$.
Suppose $\mathbb{E} X_{i}^{1}=\mathbb{E} X_{i}^{0}=0$ and $\mathbb{E}\left|X_{i}^{1}\right|^{2}=\mathbb{E}\left|X_{i}^{0}\right|^{2}=1$.

$$
\begin{gather*}
\frac{\partial}{\partial \theta} \mathbb{E} F\left(X^{\theta}\right)=\sum_{1 \leqslant n \leqslant C} K_{n} \sum_{i \in \mathcal{J}} \mathbb{E}\left(\frac{\partial}{\partial X_{i}^{\theta}}\right)^{n} F\left(X^{\theta}\right)+\text { error },  \tag{2}\\
=\sum_{3 \leqslant n \leqslant C} K_{n} \sum_{i \in \mathcal{J}} \mathbb{E}\left(\frac{\partial}{\partial X_{i}^{\theta}}\right)^{n} F\left(X^{\theta}\right)+\text { error }
\end{gather*}
$$

Since $\left(\frac{\partial}{\partial X_{i}^{\theta}}\right)^{n} F\left(X^{\theta}\right)=O(|\mathcal{J}|)^{-n / 2}$, so we obtain that

$$
\frac{\partial}{\partial \theta} \mathbb{E} F\left(X^{\theta}\right)=o(1)
$$

which implies that

$$
\mathbb{E} F\left(X^{1}\right)=\mathbb{E} F\left(X^{0}\right)+o(1)
$$

Recall

$$
\begin{equation*}
\frac{\partial}{\partial \theta} \mathbb{E} F\left(X^{\theta}\right)=\sum_{n \geqslant 1} K_{n} \sum_{i \in \mathcal{J}} \mathbb{E}\left(\frac{\partial}{\partial X_{i}^{\theta}}\right)^{n} F\left(X^{\theta}\right) \tag{3}
\end{equation*}
$$

1. $\mathbb{E}\left(\frac{\partial}{\partial X_{i}^{\theta}}\right)^{n} F\left(X^{\theta}\right)$ typically decays rapidly with increasing $n-$ as is already apparent in the simple case $F(X):=\left(|\mathcal{J}|^{-1 / 2} \sum_{i \in \mathcal{J}} X_{i}\right)^{p}$ for $p \in 2 \mathbb{N}$
2. We introduce a family of functions $\left(F_{\alpha}(X)\right)_{\alpha \in \mathcal{A}}$ that

$$
\begin{equation*}
\frac{\partial}{\partial \theta} \mathbb{E} F_{\alpha}\left(X^{\theta}\right) \leqslant C \sup _{\beta \in \mathcal{A}} \mathbb{E} F_{\beta}\left(X^{\theta}\right)+(\text { small error terms }) \tag{4}
\end{equation*}
$$

It is level-2: only $\left(F_{\alpha}(X)\right)_{\alpha \in \mathcal{A}}$ appears on both sides.

All previous proofs with Lindeberg comparison method can be replaced with this new comparison method.

## Application on random matrix: local anisotropic law

For anisotropic law: We choose

$$
F_{\mathrm{v}}(X):=(\mathrm{v},(G(X)-\Pi) \mathrm{v})^{2 p}
$$

and $\mathcal{A}=\left\{\mathbf{v}, \mathbf{e}_{i}, 1 \leqslant i \leqslant M\right\}$.

$$
\begin{equation*}
\frac{\partial}{\partial \theta} \mathbb{E} F_{\alpha}\left(X^{\theta}\right) \leqslant C \sup _{\beta \in \mathcal{A}} \mathbb{E} F_{\beta}\left(X^{\theta}\right)+(\text { small error terms }), \tag{5}
\end{equation*}
$$

Since we can bound

$$
\mathbb{E} F_{\mathbf{v}}\left(X^{\text {Gaussian }}\right)
$$

with the method mentioned in Knowles's talk, we can use selfconsistent comparison method to bound $\mathbb{E} F_{\mathrm{v}}(X)$ for general $X$.

Comparison between $Y^{0}=T^{0} X$ and $Y^{1}=T^{1} X$.

Let $T^{0}, T^{1}$ be $m \times m^{\prime}$ deterministic matrices and $X$ be $m^{\prime} \times n$ i.i.d. matrix.

$$
Y^{0}=\sum_{i j}\left(T^{0} \cdot \mathbf{e}_{i j}\right) X_{i j}, \quad Y^{1}=\sum_{i j}\left(T^{1} \cdot \mathbf{e}_{i j}\right) X_{i j}
$$

Here $\mathbf{e}_{i j}$ is $m^{\prime} \times n$ matrix with all zero entries except that $(i, j)$ entry equals to 1 .

$$
Y^{\theta}=\sum_{i j}\left(\chi_{i j}^{\theta}\left(T^{1} \cdot \mathbf{e}_{i j}\right) X_{i j}+\left(1-\chi_{i j}^{\theta}\right)\left(T^{0} \cdot \mathbf{e}_{i j}\right) X_{i j}\right)
$$

where $\chi_{i j}^{\theta}$ are i.i.d r.v. such that $\mathbb{P}\left(\chi_{i j}^{\theta}=1\right)=\theta$ and $\mathbb{P}\left(\chi_{i j}^{\theta}=0\right)=$ $1-\theta$.

Self consistent equation for $Y^{0}=T^{0} X$ and $Y^{1}=T^{1} X$.

$$
\begin{gather*}
\frac{\partial}{\partial \theta} \mathbb{E} F\left(Y^{\theta}\right)  \tag{6}\\
=\sum_{n, m \geqslant 1} K_{n, m} \sum_{i j} \mathbb{E}\left(\left(P_{i j}^{T^{0}}\right)^{n}\left(P_{i j}^{T^{1}}\right)^{m}-\left(P_{i j}^{T^{0}}\right)^{m}\left(P_{i j}^{T^{1}}\right)^{n}\right) F\left(Y^{\theta}\right) \tag{7}
\end{gather*}
$$

where $K_{n, m}$ only depends on the first $n+m$ moment of $X$ 's entries.

$$
P_{i j}^{A}=\left(A^{T} \cdot \nabla_{Y}\right)_{i j}
$$

## Application on random matrix: singular vector

Using moment flow, we can derive the distribution of singular vector of

$$
T X+\sqrt{t} X^{G}=(T, \sqrt{t} I)\left(X, X^{G}\right)^{T}, \quad t \geqslant \min (m, n)^{-1+\varepsilon}
$$

Suppose $T \geqslant 0$, with the new comparison method, we know the distribution of singular vector of

$$
\widehat{T} X=(\widehat{T}, 0)\left(X, X^{G}\right)^{T}, \quad|\widehat{T}|^{2}=|T|^{2}+t I
$$

Note: $\|(T, \sqrt{t} I)-(\widehat{T}, 0)\|$ is very small.
The general $\widehat{T}$ case can be derived similarly with some linear algebra argument.

## Moment flow method

First used by Bourgade and Yau for Wigner matrix.
The basic idea is with extended Dyson Brownian motion, one can derive a dynamic equation about
$f_{k_{1} k_{2} \cdots k_{m}}^{a_{1} a_{2} \cdots a_{m}}:=C_{a_{1} a_{2} \cdots a_{m}} \mathbb{E}\left\langle\mathbf{u}_{k_{1}}(t), \mathbf{v}\right\rangle^{2 a_{1}}\left\langle\mathbf{u}_{k_{2}}(t), \mathbf{v}\right\rangle^{2 a_{2}} \cdots\left\langle\mathbf{u}_{k_{m}}(t), \mathbf{v}\right\rangle^{2 a_{m}}$ where $\mathbf{u}_{k}(t)$ is the $k$-the eigenvector of $W+\sqrt{t} W^{G}$.

With maximum principle:

$$
\begin{gathered}
\mathcal{F}_{a}(t):=\max _{\sum_{i} a_{i}=a k_{1} k_{2} \cdots k_{m}} f_{k_{1} k_{2} \cdots k_{m}}^{a_{1} a_{2} \cdots a_{m}}, \quad a \in \mathbb{N} \\
\partial_{t} \mathcal{F}_{a}(t) \leqslant-N^{1 / 3}\left(\mathcal{F}_{a}(t)-1\right)
\end{gathered}
$$

Then $\mathcal{F}_{a}(t) \leqslant 1+o(1)$ for $t \gg N^{-1 / 3}$. Similarly with minimum principle, one obtains that

$$
f_{k_{1} k_{2} \cdots k_{m}}^{a_{1} a_{2} \cdots a_{m}}=1+o(1), \quad t \gg N^{-1 / 3}
$$

For anisotropic matrices,

$$
\begin{gathered}
f_{k_{1} k_{2} \cdots k_{m}}^{a_{1} a_{2} \cdots a_{m}} \nrightarrow 1, \quad f_{k_{1} k_{2} \cdots k_{m}}^{a_{1} a_{2} \cdots a_{m}} \rightarrow g_{k_{1} k_{2} \cdots k_{m}}^{a_{1} a_{2} \cdots a_{m}} \quad(\text { deterministic) } \\
\mathcal{F}_{a}(t):=\sum_{\sum_{i} a_{i}=a} \sum_{k_{1} k_{2} \cdots k_{m}}\left(f_{k_{1} k_{2} \cdots k_{m}}^{a_{1} a_{2} \cdots a_{m}}-g_{k_{1} k_{2} \cdots k_{m}}^{a_{1} a_{2} \cdots a_{m}}\right)^{2 p}, \quad p \in \mathbb{N}
\end{gathered}
$$

Goal:

$$
\partial_{t} \mathcal{F}_{a}(t) \leqslant-N^{1 / 3_{\mathcal{F}}} \mathcal{F}_{a}(t)
$$

Unfortunately $g_{k_{1} k_{2} \cdots k_{m}}^{a_{1} a_{2} \cdots a_{m}}$ in $\mathcal{F}_{t}$ can not be deterministic, since there is a singular term in $\partial_{t} \mathcal{F}_{a}(t)$,

$$
\frac{g_{k_{1} k_{2} \cdots k_{m}}^{a_{1} a_{2} a_{m}}-g_{k_{1} k_{2} \cdots k_{m}^{\prime}}^{a_{1} a_{2} \cdots a_{m}}}{\lambda_{k_{m}}-\lambda_{k_{m}^{\prime}}}
$$

So we define

$$
g_{k_{1} k_{2} \cdots k_{m}}^{a_{1} a_{2} \cdots a_{m}}:=g_{k_{1} k_{2} \cdots k_{m}}^{a_{1} a_{2} \cdots a_{m}}\left(\lambda_{k_{1}}, \lambda_{k_{2}}, \cdots, \lambda_{k_{m}}\right)
$$

which solve the issue of the following singular term

$$
\frac{g_{k_{1} k_{2} \cdots k_{m}}^{a_{1} a_{2} a_{m}}-g_{k_{1} k_{2} \cdots k_{m}^{\prime}}^{a_{1} a_{2} \cdots a_{m}}}{\lambda_{k_{m}}-\lambda_{k_{m}^{\prime}}}
$$

Then differential equation becomes stochastic differential equation.

$$
\partial_{t} \mathcal{F}_{a}(t) \leqslant-N^{1 / 3_{\mathcal{F}}^{a}}(t)+\text { error term }+O(1) \mathrm{d} B
$$

Advantage: The limit of $f_{k_{1} k_{2} \cdots k_{m}}^{a_{1} a_{2} \cdots a_{m}}(t)$ is allowed to depend on $k_{1} k_{2} \cdots k_{m}$ and $a_{1} a_{2} \cdots a_{m}$.

Further applications will appear in future work.

Thank you

